

Dealing with Uncertainty in the Smart Grid: A Learning Game Approach

Hélène Le Cadre (helene.le_cadre@mines-paristech.fr)

Jean-Sébastien Bedo (jean-sebastien.bedo@m4x.org)

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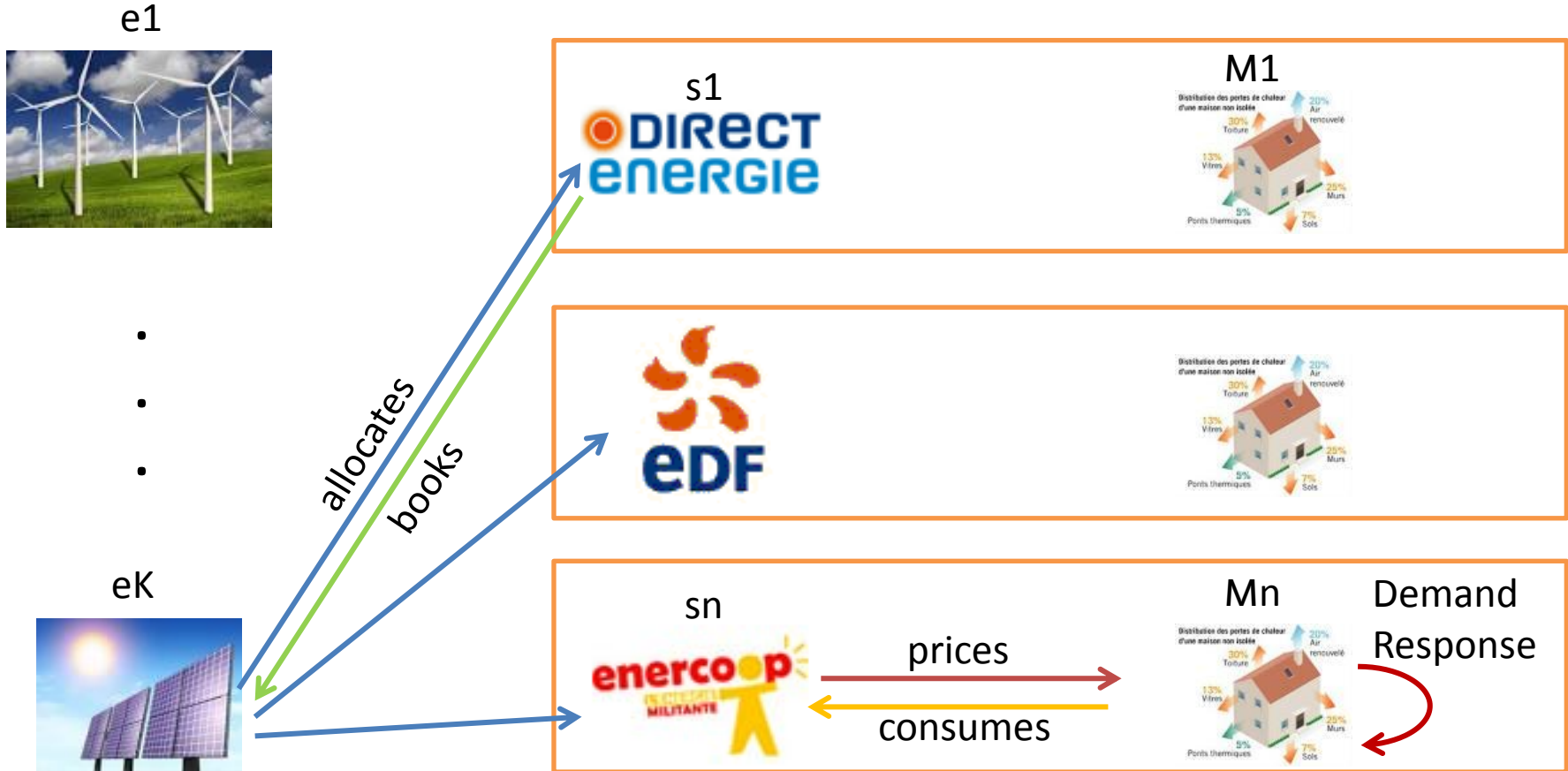
Objectives

- Define an optimal learning algorithm to deal with renewable energies uncertainty
 - Calculate bounds on the profit risk linked to forecast errors
 - Estimate learning speed
- Evaluate the incentives for energy providers to enter into a coalition in a learning context

Agents overview

- Energy producers (e_1, \dots, e_K)
 - We focus on renewable energy (wind, solar, etc.) which are unpredictable
 - We denote the energy productions by $v_k^e(t)$, which are individual sequences
- Energy service providers (s_1, \dots, s_n)
 - We do not take into account energy transport costs and constraints
- Captive consumers ($\mathcal{M}_1, \dots, \mathcal{M}_n$)
 - We consider both local energy production and demand response mechanisms
 - We denote the energy net demands by $v_i^s(t)$, which are individual sequences

Our model is based on a Stackelberg Game



Customers optimization program

- \mathcal{M}_i net demand reaches $v_i^s(t)$ energy units for time period t
- \mathcal{M}_i decides to perform Demand Response by
 - postponing the consumption of $a_i(t)$ energy units
 - buying the rest $v_i^s(t) - a_i(t)$ to provider s_i
- The quantity of DR is chosen so as to minimize the total cost of energy $\underbrace{\left(v_i^s(t) - a_i(t)\right) p_i(t)}_{\text{Consumption cost}} + \underbrace{c(a_i(t))}_{\text{DR cost}}$
- Under a quadratic DR cost, we find that, at equilibrium, $a_i(t) = p_i(t)$

Service providers optimization program 1/2

- The energy procurement market is divided in 2 steps
 1. Each provider s_i books $q_{ik}(t)$ energy units to e_k .
 2. e_k allocates its production $v_k^e(t)$ proportionally to the bookings. We denote $\alpha_{ki}(t)$ the share obtained by s_i .
- The profit of service provider s_i at each time period t is then the sum of three components:

1 the revenues from the retail market

$$(v_i^s(t) - a_i(t))p_i(t)$$

2 the costs of energy booking towards producers

$$- \sum_{k=1 \dots K} q_{ik}(t) \widetilde{p}_k(t)$$

3 a cost related to energy shortage if the energy provided by renewable producers is not sufficient to satisfy the demand of s_i customers

$$- \gamma_i \left[(v_i^s(t) - a_i(t)) - \sum_{k=1 \dots K} \alpha_{ki}(t) v_k^e(t) \right]_+$$

Service providers optimization program 2/2

- Under fair energy shortage costs, if energy shortage is nearly certain, i.e. $v_i^s(t) \geq \gamma_i + 2\alpha_i \sum_{k=1 \dots K} v_k^e(t)$, si will define its price and energy bookings such that

$$\left\{ \begin{array}{l} p_i(t) = \frac{\nu_i^s(t) + \gamma_i}{2} \\ q_{ik}(t) = \frac{\nu_k^e(t)}{\tilde{p}_k(t)} \frac{n-1}{\delta \tilde{\gamma}_i} \alpha(i) \end{array} \right.$$

- Else, si will book a minimum of energy and decrease its price to avoid energy shortage
- We assume that we are in the first case, which fits well to today situation, where renewable energy is the minority

Energy producers optimization program

- The profit of energy producer e_k at each time period is the sum of two components:

- 1 the revenues of energy bookings

$$\widetilde{p}_k(t) \sum_{i=1 \dots n} q_{ik}(t)$$

- 2 a cost related to energy shortage if the energy provided to each s_i is lower than its previous booking

$$-\widetilde{\gamma}_i [q_{ik}(t) - \alpha_{ki}(t)v_k^e(t)]_+$$

The energy producers can avoid energy shortage costs by fixing their price to $\frac{n-1}{\delta \min \widetilde{\gamma}_i'}$, which is independent of production and demand.

Learning Game Description

➤ Only service providers must forecast energy demand and energy production to optimize their profit

- We denote by
 - $f_i(x)$ the forecast made by s_i for the value x
 - $f_i(t)$ all the forecasts made by s_i at time period t
 - $f_{-i}(t)$ all the forecasts made by other service providers than s_i at time period t
 - $f(t) = (f_i(t), f_{-i}(t))$
 - $v(t)$ the vector of energy productions and demands at time period t
 - $\pi_i(f_i(t), f_{-i}(t), v(t))$ the profit of service provider s_i

Optimal learning strategies

- Loss: the difference between the profit obtained with an exact forecast and the observed profit
 - $l_i(f(t), v(t)) = \pi_i(v(t), f_{-i}(t), v(t)) - \pi_i(f(t), v(t))$
- External regret: the difference between the observed cumulative loss and the cumulative loss of the best constant prediction (pure strategy)
 - $R_i(T) = \sum_{t=1}^T l_i(f(t), v(t)) - \min_y \sum_{t=1}^T l_i(y, f_{-i}(t), v(t))$
- A Hannan consistent learning strategy is such that
$$\lim_{T \rightarrow +\infty} \frac{1}{T} R_i(T) = 0$$

A Hannan consistent learning strategy exists for each provider s_i .

External regret Learning Algorithm

Initialization. For $t = 0$, we set: $w_0(x) = \frac{1}{|\mathcal{E}|}$, $\forall x \in \mathcal{E}$.

Step 1 to T. The updating rules are the following:

$$\begin{aligned}d_t(x) &= \frac{w_t(x)}{\sum_{x \in \mathcal{E}} w_t(x)}, \forall x \in \mathcal{E} \\w_{t+1}(x) &= \exp \left(\eta_{t+1} \sum_{s=1}^t H_X(x, s) \right) \\&= w_t(x)^{\frac{\eta_{t+1}}{\eta_t}} \exp \left(\eta_{t+1} H_X(x, t) \right), \forall x \in \mathcal{E} \\\eta_{t+1} &= \min \left\{ \frac{1}{2 \max\{|H_X|\}}; \sqrt{\frac{2(\sqrt{2}-1)}{e-2}} \sqrt{\frac{\ln|\mathcal{E}|}{\vartheta_t}} \right\} \\\vartheta_{t+1} &= \vartheta_t + \text{Var} \left(H_X(X_{t+1}, t+1) \right)\end{aligned}$$

where H_X is the payoff function associated to the forecast made by s_i for the value X . It corresponds to the terms of provider s_i profit equation depending only on X . $H_X(y, t)$ is the payoff value for making the forecast y at time period t .

The external regret learning algorithm is a Hannan consistent forecasting strategy for s_i .

Coalition learning strategy

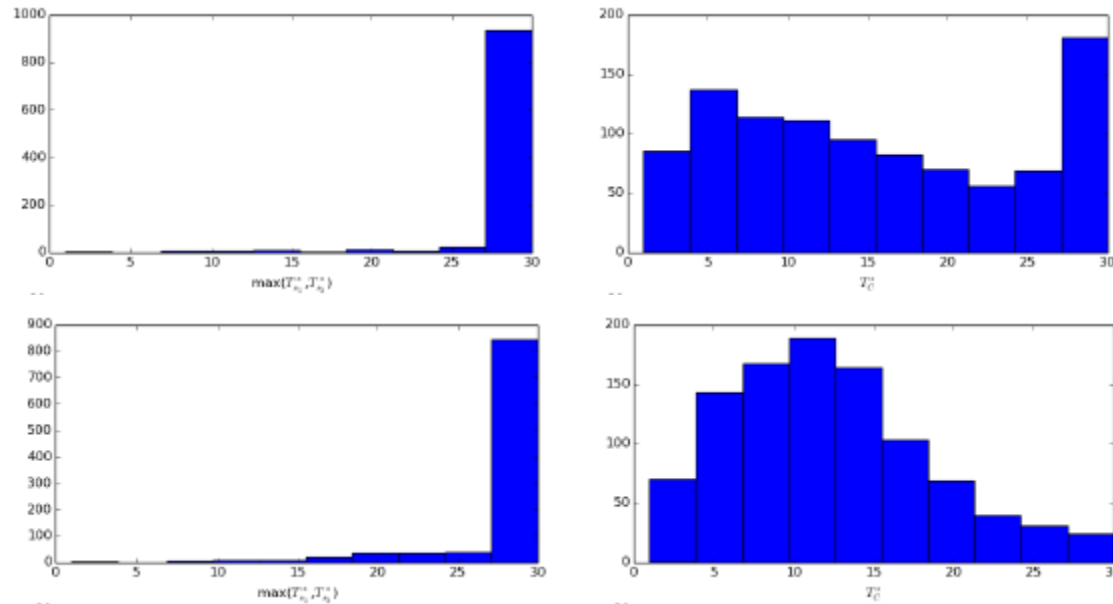
- A coalition of providers is a group of providers who collaborate to learn the hidden energy productions. They align their predictions on a common value.
- Independent learning payoff

$$H_{f_i(\nu_k^e)}(x, t) = -\frac{\alpha(i)}{\tilde{\gamma}_i} \frac{n-1}{\delta} x - \gamma_i \left(\nu_i^s(t) - \frac{f_i(\nu_i^s, t) + \gamma_i}{2} \right. \\ \left. - \sum_{l \neq k} \frac{\alpha(i) f_i(\nu_l^e, t)}{\sum_{j=1, \dots, n} \alpha(j) f_j(\nu_l^e, t)} \nu_l^e(t) - \frac{\alpha(i) x}{\sum_{j \neq i} \alpha(j) f_j(\nu_k^e, t) + \alpha(i) x} \nu_k^e(t) \right) +$$

- Coalition learning payoff

$$H_{f(v_k^e)}(x, t) = -\frac{n-1}{\delta} x \sum_i \frac{\alpha(i)}{\tilde{\gamma}_i} \quad \triangleright \text{time independent}$$

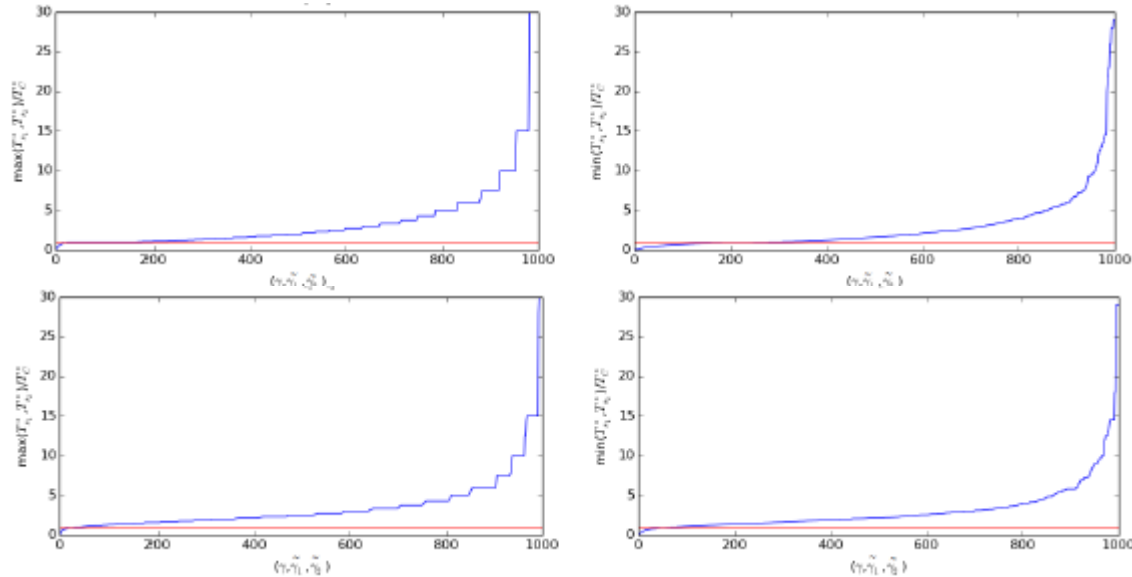
Results : convergence time



30 = not converged

- Convergence times are smaller
 - For the grand coalition than under distributed learning
 - Under internal regret minimization than under external regret minimization

Results : Will a grand coalition emerge?



- A grand coalition has 85% (resp. 98:5%) of chances to emerge under external (resp. internal) regret minimization

Conclusion

- Summary
 - We have used random individual sequences which do not require an a priori probabilistic structure.
 - Only energy service providers must forecast energy demands and productions.
 - They can decrease their average profit risk by sharing information and aligning their forecasts.
 - They often have individual incentives to do so.
 - It speeds up the market convergence.
- Ideas to be explored
 - Exogenous prices
 - Non captive consumers
 - Add transport costs and constraints
 - Use energy shortage costs to reach an energy mix target