A short-term model for the oil industry addressing commercial storage

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Outline

- 1 Introduction
- 2 The short-term model

3 Numerical simulations and discussion of the results

The oil industry has had unique specificities for many decades

- A monopolistic coalition (OPEC) drives the market and the industry
- The demand of oil is extremely inelastic w.r.t. price, so that a small increase
 in the cartel's production drives prices down by a significant amount
- There has always been two decades of production ahead:
 Hotelling framework (exhaustible resource) is not relevant on the considered time scales
- For now 30 years, the market share of OPEC has been stable around 42%
- Borrowing constraints bind the investments of non-OPEC producers: for most small producers, investments depend on the price of the barrel.
 Producers invest at the same time, which generates investment inefficiency
- Commercial storage is less than 10 % of the annual production.
 Nevertheless, commercial storage is key to understand short-term behaviours

Two models

- A long-term model for OPEC versus a competitive fringe of classic-oil producers, on the time scale of several decades
- 2 A short-term model involving OPEC and a crowd of arbitrageurs who store and sell the resource:
 - the behaviour of the competitive fringe of classic-oil producers is described in a simplified way
 - the time scale is of the order of some years

Not addressed yet:

shale oil (fracking)

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The different agents

- A major agent (a monopolistic cartel producing a natural resource: OPEC)
- A competitive fringe of small producers
- A set of competitive risk-neutral physical arbitrageurs, who store and sell the resource
- The consumers

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Important feature: the arbitrageurs will most often limit the evolution of the price. But, when storage capacity limits are reached, the strategic power of the cartel increases dramatically. When storage is at its minimal level, the cartel has the power to drive prices up by cutting production; conversely, when storage is at its maximal level, the cartel can drive prices down by increasing production.

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In order to focus on the interactions between the cartel and the arbitrageurs,

- we will not consider the decision making process of the small producers. Instead, we assume that the dynamics of their aggregate production is given as a function of the current state variables
- The demand of the resource will be a simple decreasing function of the price

Two state variables

- \bullet k: the level of commercial storage
- lacktriangledown z: the aggregate production of the competitive fringe

Physical storage capacity limits: $k \in [k_{\min}, k_{\max}]$ will play a key role

Equilibrium

We look for a stationary equilibrium between the cartel and the arbitrageurs who store the resource:

- the cartel solves an optimal control problem given the price of the resource.

 The optimal value is a function U(k, z)
- The price of the resource, described by a function p(k, z), is fixed by the arbitrageurs when they are not bound by physical storage limits

Mathematically, the functions U and p will satisfy a system of 2 coupled PDEs with **highly non standard boundary conditions**

The demand of the resource

After a suitable change of units, the demand of the resource is given by

$$D(p_t) = 1 - \epsilon p_t,$$

where p_t is the price of the resource

The elasticity ϵ of the demand is very small

On the short term, such a linear demand function fits well the observed data in the usual range of oil prices

The dynamics of the fringe output z_t (1/2)

To keep the model simple, we do not address the decision making process of non-OPEC producers; we rather assume that the dynamics of z_t is given:

$$dz_t = b(k_t, z_t, p_t)dt + \sqrt{2\nu_z}dB_t$$

where

$$b(k, z, p) = \kappa(\lambda p - \mu) + f(k) + \widetilde{b}(z).$$

- ν_z is a small nonnegative constant, possibly 0
- $\kappa(\lambda p \mu)$ describes the direct impact of prices on the investments of the fringe producers, hence on their production capacity
- $\bullet \; \tilde{b}(z)$ appears only for technical reasons and is not zero only for z very small or very large

The dynamics of the fringe production z_t (2/2)

$$dz_t = b(k_t, z_t, p_t)dt + \sqrt{2\nu_z}dB_t$$
 with $b(k, z, p) = \kappa(\lambda p - \mu) + f(k) + \widetilde{b}(z)$

• A typical possible choice for f(k) is

$$f(k) = a_1 \left(\frac{k_{\text{max}} - k}{k_{\text{max}} - k_{\text{min}}}\right)^2 - a_2 \left(\frac{k - k_{\text{min}}}{k_{\text{max}} - k_{\text{min}}}\right)^2$$

with suitable $a_1 > 0$ and $a_2 > 0$. The term f(k) is significant only for $k \approx k_{\min}$ and $k \approx k_{\max}$, and accounts for a little increase (resp. decrease) in production capacities when the storage facilities are close to empty (resp. full).

f(k) is a proxy for the time delays between the investment decisions of the fringe producers and the actual creation of new capacities of production.

Indeed, close to empty storage must follow a period when the price is high, thus the investments of the producers in the competitive fringe are at a high level; the latter results in an increase of production capacity, i.e. an increase of z, even if the instantaneous price has decreased.

• The mechanism has to be reversed when the storage facilities are close to full.

The dynamics of the commercial storage k_t

The control variable of the cartel is its production rate q_t

Matching demand and supply yields

$$dk_t + D(p_t)dt = (q_t + z_t)dt$$

or, adding noise,

$$dk_t = (q_t + z_t - D(p_t))dt + \sigma(k_t)dW_t$$

The volatility $\sigma(k)$ vanishes at $k = k_{\min}$ and $k = k_{\max}$, to avoid singular behavior due to the state constraints $k_{\min} < k < k_{\max}$

The optimal control problem faced by the cartel

Costs

- a production cost: cqt
- a penalty term $\alpha/2 (q_t q_0)^2$: q_0 is the target market share of the cartel. OPEC has had a market share of $\approx 42\%$ for more than three decades

Guessing $p_t = p(k_t, z_t)$, the cartel solves the optimal control problem

$$U(k,z) = \sup_{q_t} \mathbb{E}\left(\int_0^\infty e^{-rt} \left((p_t - c)q_t - \frac{\alpha}{2} (q_t - q_o)^2 \right) dt \quad \bigg| z_0 = z, k_0 = k \right)$$

Hence, introducing the Hamiltonian

$$H(z, p, \xi) = \sup_{q \ge 0} \left((p - c)q - \frac{\alpha}{2} (q - q_0)^2 + (q + z - D(p)) \xi \right)$$

= $\frac{1}{2\alpha} (p - c + \xi)^2 + \xi (z - D(p)) + q_0 (p - c - \xi),$

we get the HJB equation:

$$-rU + H(z, p, \partial_k U) + b(k, z, p)\partial_z U + \frac{\sigma^2(k)}{2}\partial_{kk} U = 0$$

The arbitrageurs

Cost of storage: the cost of storing a unit of resource per unit of time is g(k) when the level of storage is k

Since storers are risk-neutral and face a cost of storage that depends on the amount stored, a symmetric equilibrium requires that if $k_{\min} < k_t < k_{\max}$, then

$$p_{t} = \mathbb{E}\left(\left.e^{-r\delta t}p_{t+\delta t} - \int_{t}^{t+\delta t}g(k_{s})ds\right|(k_{t}, z_{t})\right)$$

Ito calculus then leads to the equation:

$$-rp + D_{\xi}H(z, p, \partial_k U)\partial_k p + b(k, z, p)\partial_z p + \frac{\sigma^2(k)}{2}\partial_{kk}p = g(k)$$

Summary

The system of PDEs satisfied by U, p is

$$\begin{cases} 0 &= -rU + H(z, p, \partial_k U) + b(k, z, p) \partial_z U + \frac{\sigma^2(k)}{2} \partial_{kk} U \\ \\ 0 &= -rp + D_{\xi} H(z, p, \partial_k U) \partial_k p + b(k, z, p) \partial_z p + \frac{\sigma^2(k)}{2} \partial_{kk} p - g(k) \end{cases}$$

for $k_{\min} < k < k_{\max}$ and $z_{\min} < z < z_{\max}$,

with

$$\begin{split} H(z,p,\xi) &= \sup_{q \geq 0} \left(-\frac{\alpha}{2} (q - q_{\circ})^{2} + (p - c)q + (q + z - D(p)) \xi \right) \\ &= \frac{1}{2\alpha} (p - c + \xi)^{2} + \xi (z - D(p)) + q_{\circ} (p - c - \xi) \end{split}$$

Comments on the system of PDEs

Connections with mean field games involving a major agent

- The system of PDEs couples a HJB equation for the cartel (major agent) and an equation of the type master equation for the price of the resource
- In the present case, the master equation does not model a crowd of players as in MFGs, but rather an equilibrium reached by the crowd of physical arbitrageurs
- It seems possible to refine the present model by considering that the physical arbitrageurs play a MFG. This would lead to a more involved model of a MFG with a major agent

Boundary conditions at $k = k_{\min}$ and $k = k_{\max}$

For the boundary conditions linked to the state constraints $k_{\min} \leq k_t \leq k_{\max}$, it is useful to define:

• the nonincreasing and nondecreasing envelopes of $\xi \mapsto H(z, p, \xi)$:

$$\begin{array}{lcl} H_{\downarrow}(z,p,\xi) & = & \displaystyle \max_{q \leq D(p)-z} \left(-\frac{\alpha}{2} (q-q_{\circ})^2 + (p-c)q + \xi(q+z-D(p)) \right) \\ H_{\uparrow}(z,p,\xi) & = & \displaystyle \max_{q \geq D(p)-z} \left(-\frac{\alpha}{2} (q-q_{\circ})^2 + (p-c)q + \xi(q+z-D(p)) \right) \end{array}$$

 $H_{\perp}(z,p,\xi)$ corresponds to the controls q such that the drift of k_t is nonpositive $H_{\uparrow}(z, p, \xi)$ corresponds to the controls q such that the drift of k_t is nonnegative

• the quantity:

$$H_{\min}(z,p) = \min_{\xi} H(z,p,\xi) = -\frac{\alpha}{2} \left(D(p) - z - q_{\circ} \right)^{2} + (p-c)(D(p) - z)$$

which corresponds to the control q = D(p) - z for which the drift of k_t vanishes

$$k_t \geq k_{\min}, \quad \forall t \qquad \Rightarrow \qquad D_{\xi} H\Big(z, p(k_{\min}, z), \partial_k U(k_{\min}, z)\Big) \geq 0$$

Two cases may occur:

$$k_t \geq k_{\min}, \quad \forall t$$
 \Rightarrow $D_{\xi} H\Big(z, p(k_{\min}, z), \partial_k U(k_{\min}, z)\Big) \geq 0$

Two cases may occur:

① $D_{\xi}H(z,p,\partial_k U)>0$ for k near k_{\min} : then no boundary condition is needed for p at (k_{\min},z)

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- ① $D_{\xi}H(z,p,\partial_k U) > 0$ for k near k_{\min} : then no boundary condition is needed for p at (k_{\min},z)
- 2 $D_{\xi}H(z,p,\partial_k U) \leq 0$ for k near k_{\min} : then there must hold

$$D_{\xi}H(z, p(k_{\min}, z), \partial_k U(k_{\min}, z)) = 0$$
 \Leftrightarrow $q + z - D(p) = 0.$

This implies that p can be considered as the control variable at $k = k_{\min}$. In other words, the cartel directly controls the price in this situation.

$$k_t \geq k_{\min}, \quad \forall t$$
 \Rightarrow $D_{\xi} H\Big(z, p(k_{\min}, z), \partial_k U(k_{\min}, z)\Big) \geq 0$

Two cases may occur:

- ① $D_{\varepsilon}H(z,p,\partial_k U)>0$ for k near k_{\min} : then no boundary condition is needed for p at (k_{\min}, z)
- 2 $D_{\varepsilon}H(z,p,\partial_k U) \leq 0$ for k near k_{\min} : then there must hold

$$D_{\xi}H(z, p(k_{\min}, z), \partial_k U(k_{\min}, z)) = 0 \qquad \Leftrightarrow \qquad q + z - D(p) = 0.$$

This implies that p can be considered as the control variable at $k = k_{\min}$. In other words, the cartel directly controls the price in this situation.

In this case, we also expect that p is nonincreasing with respect to kfor $k \approx k_{\min}$, which implies that

$$rp \ge b(k_{\min}, z)\partial_z p - g(k_{\min}).$$

Indeed, if p was increasing with respect to k at $k \approx k_{\min}$, then the agents owning the storage facilities would make an arbitrage and increase the stored quantity, and the drift of k_t would be positive.

Boundary conditions at $k = k_{\min}$, when $D_{\xi}H(z, p, \partial_k U) \leq 0$ for $k = k_{\min,+}$.

• Therefore, when $z_t = z$, among the strategies consisting of maintaining k_t at the minimal value k_{\min} , the optimal one is

$$\left\{ \begin{array}{lcl} q^* & = & 1 - z - \epsilon p^*, \\ \\ p^* & = & \underset{r\pi \geq b(k_{\min},z)\partial_z \pi - g(k_{\min})}{\operatorname{argmax}} F(\pi,\partial_z U) \end{array} \right.$$

where

$$F(\pi, \partial_z U) = H_{\min}(z, \pi) + b(k_{\min}, z)\partial_z U$$

in view of the PDE for U.

Note that p^* depends on $\partial_z U$, $\partial_z p$.

• In this situation, the boundary condition for p at $k = k_{\min}$ is

$$p(k_{\min}, z) = p^*(\partial_z U, \partial_z p)$$

Summary

• The system of PDEs for $k_{\min} < k < k_{\max}$ is

$$\begin{cases} 0 = -rU + H(z, p, \partial_k U) + b(k, z)\partial_z U + \frac{\sigma^2(k)}{2}\partial_{kk} U \\ 0 = -rp + D_\xi H(z, p, \partial_k U)\partial_k p + b(k, z)\partial_z p + \frac{\sigma^2(k)}{2}\partial_{kk} p - g(k) \end{cases}$$

• At $k = k_{\min}$,

$$rU = \max(A, B)$$

with

$$\begin{cases} A = H_{\uparrow}(z, p(k_{\min}, +, z), \partial_k U) + b(k_{\min}, z) \partial_z U & \text{positive optimal drift} \\ B = \max_{r\pi > b(k_{\min}, z) \partial_z \pi - g(k_{\min})} H_{\min}(z, \pi) + b(k_{\min}, z) \partial_z U & \text{optimal drift} = 0 \end{cases}$$

Boundary condition for p: in the weak sense,

$$p = p^*(\partial_z U, \partial_z p)$$

Comments on the boundary conditions

- \bullet The boundary conditions at $k=k_{\min}$ and $k=k_{\max}$ arise from the physical constraints on the storage capacity. These constraints play a key role. Indeed, in some situations and when the storage level is either minimal or maximal, the cartel directly controls the price of the resource
- The resulting boundary conditions at $k = k_{\min}$ and $k = k_{\max}$ are very unusual from the mathematical point of view, in fact new to the best of our knowledge
- Obtaining a complete mathematical theory seems to be a difficult open problem
- On the theoretical viewpoint, our main results deal with asymptotic expansions of solutions

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The numerical scheme for the system of PDEs

Main ideas

- A monotone finite difference method for the HJB equation and the boundary conditions on U due to state constraints (upwinding in the discrete Hamiltonian)
- A monotone finite difference method for the price p. The advection speed in the discrete PDE is consistent with the discrete version of the Hamiltonian in the HJB equation
- The resulting discrete system is solved by a long time approximation involving an explicit time scheme
 - The reason for choosing an explicit scheme lies in the complexity of the boundary conditions
 - Finding an implicit or semi-implicit scheme consistent with the nonlinear boundary conditions seems challenging

The parameters of the model

$$k_{\min} = 0$$
, $k_{\max} = 0.05$, $z_{\min} = 0.35$, $z_{\max} = 0.75$,

$$b(k, z, p) = a \left(\frac{k_{\text{max}} - k}{k_{\text{max}} - k_{\text{min}}}\right)^2 - a \left(\frac{k - k_{\text{min}}}{k_{\text{max}} - k_{\text{min}}}\right)^2 + \kappa(\lambda p - \mu)$$
$$g(k) = 0$$

with

$$r = 0.1,$$

$$\epsilon = 4. \ 10^{-4}$$

$$a = 0.01$$

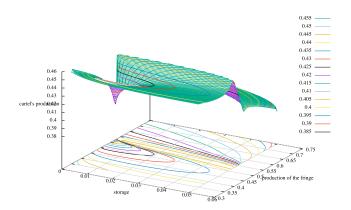
$$\kappa = 2 \ 10^{-3}, \quad \lambda = 0.4, \quad \mu = 25$$

$$q_0 = 0.42, \quad \alpha = 10^4$$

$$c = 10$$

$$\nu_z \approx 10^{-4}, \quad \sigma(k) = 0, \text{ for all } k$$

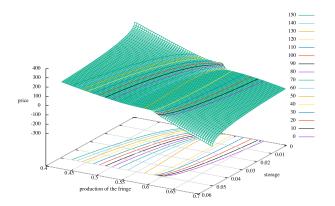
The optimal production of the cartel: $(k, z) \mapsto q^*(k, z)$



The optimal production level of the cartel as a function of k and z.

Note the shock, whose amplitude is maximal at $k = k_{\min}$ and vanishes at $k = k_{\max}$

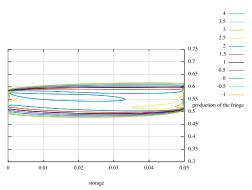
The price of the resource: $(k, z) \mapsto p(k, z)$



The price as a function of k and z

There is also a shock in the price

The invariant measure



The contours of the invariant measure of (k_t, z_t) (in log. scale)

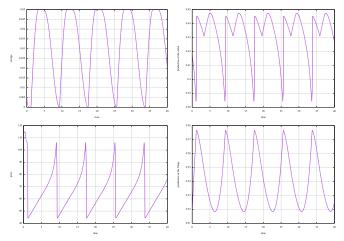
The invariant measure is concentrated around a stable cycle

Within the cycle, the density is much higher in the region close to $k = k_{\min}$ and k_{\max} , because the evolution is slow there

Simulations of the trajectories from the optimal feedback laws

- With the functions U and p computed by the finite difference method, yielding the optimal feedback, we neglected the Gaussian noise (which is besides small in the present case) and simulated the evolution of k_t and z_t by means of a standard Euler scheme
- We see that after a small time, the trajectory becomes time-periodic, with a period of the order of 7.5 years
- lacktriangledown In reality, there is noise. Thus the cycles are not so evident and so regular

Simulations of the trajectories from the optimal feedback laws

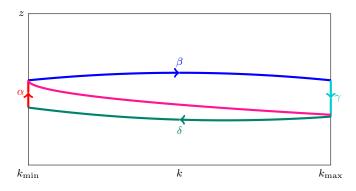


A stable cycle:

Top-Left: the level of storage vs. t. Top-Right: the production of the cartel vs. t. Bottom-Left: the price vs. t. Bottom-Right: the production of the fringe vs. t.

The observed cycle and its interpretation

The cycle observed in the numerical simulations is drawn schematically. In the absence of significant randomness, we can make out four phases



The cycle $\alpha, \beta, \gamma, \delta$ in the (k, z) plane. In pink, the shock line

Numerical simulations and discussion of the results

The first phase of the cycle: $k \approx k_{\min}$

Storage is close to minimal. The monopolistic cartel has the power to drive the price up by maintaining a low level of production.

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This explains the strategic shock that appears clearly in the simulation; indeed, it can be seen that when storage is minimal, the production of the monopolistic cartel increases brutally when z, the production of the fringe crosses a critical value. This brutal increase in production makes the price fall. This phenomenon has been observed in 2015 and 2020.

The last three phases of the cycle

- Phase (β) : When the price has fallen, the stored quantity of resource increases rapidly, and the state (k_t, z_t) is drifted to the right with a velocity nearly parallel to the k-axis. After having brutally increased its production, the cartel may let it decrease smoothly until storage gets full.
- Phase (γ) : Storage is full. The monopolistic cartel can now increase its production again and maintain the low level of price as long as necessary in order to deter the fringe from investing. The production of the fringe, z, decreases to the value that suits the cartel.
- Phase (δ) : Since the value of z is low enough, the monopolistic cartel may reduce its production. Then the stored quantity of resource decreases and the price is driven up more rapidly than in the phases β and γ .

Discussion on what happened in 2015

In 2015, OPEC decided to reconquer the market share that had been lost due to the fast development of the US shale industry from 2009 to 2015.

The price drop was then strong and sudden: prices dropped from \$100 to \$40 per barrel in a few months.

At that time, this price drop was analyzed as an attack against US shale. In the spirit of the present model, it was rather an attack against all competitors, aimed at recovering market share.

Indeed, the OPEC strategy had a strong impact not only on the US shale industry, which in fact, proved strong resiliency and coping abilities, but on many other fringe producers.

Discussion on what happened in 2020 (1/2)

In 2020, an exogenous shock to demand occurred in the first quarter of the year, with a magnitude of the order of ten times the standard deviation of demand.

Although it was not designed to handle such situations, our model seems to give an explanation of what happened.

Recall that in the present model, z (resp. q) is the ratio of the non OPEC capacity of production to the global level of demand, (resp. the ratio of the OPEC production to the global level of demand).

In the first semester of 2020, the sanitary crisis resulted in an unexpected and exceptional drop of the global demand, of the order of 10% to 15%. Therefore, the variable z got suddenly increased by 10% to 15%, and the monopolistic cartel got carried to the upper side of the shock.

In our model, the optimal response was to increase immediately production. This is precisely what happened to the surprise of many.

Discussion on what happened in 2020 (2/2)

Many observers considered that what seemed a conflict between OPEC and Russia, which led to an increase in production while the demand collapsed, was suicidal.

However, from the viewpoint of our model, this strategy was simply intended at reducing the capacity of production of the competitors as fast as possible.

Indeed, as soon as OPEC had increased its production after the collapse of the demand, storage became rapidly full. The maximal level $k_{\rm max}$ was reached in a few weeks, and the cartel could drive prices to a very low level (prices even went negative during a very short period).

Many planned investments stopped, and some production units were definitely closed.

After this period, OPEC started to strongly reduce its production.