# An Efficient SSP-based Methodology for Assessing Climate Risks of a Large Credit Portfolio

based on joint work with

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Séminaire FiME - IHP, Paris - 24 Janvier 2025



bjective

Climate risks Shared Socioeconomic Pathway Overview of methodology

# Objective

To model and sample the cumulative credit loss

$$\mathcal{L} = \sum_{i=1}^n \Lambda^i imes \mathbf{1}_{\{X^i \le d^i\}}$$

where

- $\Lambda^{i} = \text{EAD}^{i} \times \text{LGD}^{i}$  and large  $n \ (\approx 1E6)$  of obligors,
- *d<sup>i</sup>* represents the default barrier of the *i*th obligor,
- X<sup>i</sup> is the obligor's default-relevant variable.

#### ▲ How to include climate risks in the picture?

Objective **Climate risks** Shared Socioeconomic Pathways Overview of methodology

# Risk management in climate finance

Climate risks in finance: Carney speech in 2015 on "breaking the tragedy of the horizon". *Physical and transition risks.* 

- Physical risks: Economic costs and financial losses resulting from the increasing severity and frequency of extreme climate change-related weather events (heatwaves, landslides, floods, wildfires and storms), longer-term gradual shifts of the climate (extreme weather variability, ocean acidification, rising sea levels and average temperatures), loss of ecosystem and services (desertification, water shortage, degradation of soil quality or marine ecology)...
- Transition risks: risks related to the process of adjustment towards a low-carbon economy, it concerns social and political instability of policies in this period as well as technological changes.
- See BIS document "Climate-related risk drivers and their transmission channels", April 2021.

Today's talk:

\* modelling of the transmission channel "transition risk" and "physical risk" to "credit risk"

\* aggregate them in a large portfolio of obligers 👍 🚛 🚛 🚛 🔊 👁 🔧

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# Building Forward-looking scenarios

 Since 1988, the Intergovernmental Panel on Climate Change (IPCC) has published Special Reports summarizing different potential macro-scenarios RCPs (Representative Concentration Pathways) of global warming and related risks.

These scenarios are based on IAMs (Integrated Assessment Models), developed by scientists and economists.

Examples: possible increases of global temperature by 2100 are  $0.3^{\circ}$ C-1.7°C (RCP2.6),  $1.1^{\circ}$ C-2.6°C (RCP4.5),  $1.4^{\circ}$ C-3.1°C (RCP6.0), and  $2.6^{\circ}$ C-4.8°C (RCP8.5).

• Many other possible scenarios are being developed in the scientific literature subject to different ecological transition trajectories, sectors, countries, etc.

Shared Socioeconomic Pathways (SSP)

See  $[RvVK^+17]$  for an overview.

Data available on the SSP Public Database

https://tntcat.iiasa.ac.at/SspDb \_ ,

#### Context

Modeling climate risk for obligors Aggregation in the portfolio Numerical experiments Conclusion Objective Climate risks Shared Socioeconomic Pathways

Overview of methodology



Figure: Left: SSPs narratives overview. Right: RCP/SSP combinations.

Context

Modeling climate risk for obligors Aggregation in the portfolio Numerical experiments Conclusion Objective Climate risko Shared Socioeconomic Pathways

# Examples of SSP



Figure: Historical and scenario-based CO2 emission, from 1980 to 2100, in Mt/yr in the OECD, according to the activity sectors: Energy (top left), Industry (top right), Residential Commercial (bottom left), Transportation (bottom right). Figure: Global average temperature increase  $\mathcal{T}_{ATM}$  relative to the pre-industrial era (year 1750) for different SSPs.





# Modeling transition risks

 $\triangleright$  We model how the obligor production can be impacted by the future policies of CO2 emission. Stochastic model with energy parameters as inputs.

Depending on how and where these energy sources are produced, their climate impact and price are different.

Source of Energy	Emission factors (kgCO <sub>2</sub> e per kWh)
Electricity (Coal)	0.820
Electricity (Gas)	0.490
Electricity (Wind)	0.011
Electricity (Nuclear)	0.012
Electricity (Hydro)	0.024
Charcoal	0.403
Crude Oil	0.264
Natural Gas	0.202

 Table: A few examples of emission factors (sometimes called emission intensity or carbon output rate).

 carbon output rate).
 carbon output rate).

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Supplier	Coal	Gas	Nuclear	Renewable	Other	Emission factor
						$(kgCO_2e per kWh)$
Utilita	9.0	74.0	7.0	3.0	8.0	0.429
e.on	2.0	16.1	1.5	78.8	1.6	0.093
EDF Energy	1.6	15.1	63.1	19.0	1.2	0.082
Bulb	0	0	0	100.0	0	$\approx 0$

Table: Fuel Mix (in %) of some of the UK Domestic Electricity Suppliers as of 2022.

NB: Because of The Electricity (Fuel Mix Disclosure) Regulations Act of 2005, electric suppliers are obligated to provide details of the mix of fuels used to produce electricity.

Transition risks

#### $\triangleright$ Impact of location and date



Figure: Left: emission factors of electricity in  $kgCO_2e/kWh$  as a function of time for France, the USA, and China. Right: Bar plots of the electricity mix as of 2022 for the same countries.

Transition risks

#### $\triangleright$ Impact of energy price



Figure: Left: Yearly US average price of Gasoline in USD/liter. Right: Yearly US average prices of household gas and electricity in USD/kWh.

# Stochastic model for the production

- n obligors
- n+1 independent standard Brownian motions
- one common systemic factor B, n independent idiosyncratic risk factors  $B^i$
- Log-production  $p_t^i = \log(P_t^i)$  solves:

$$dp_t^i = (a^i - b^i p_t^i + c_{\bullet}^{i,\theta} \cdot \gamma_{\bullet,t}^i) dt + \sigma^i \left( \rho^i dB_t + \sqrt{1 - (\rho^i)^2} dB_t^i \right),$$
$$c_{\bullet}^{i,\theta} := (c_e^i \times \theta_{e,t}^i)_{e \in \mathscr{E}^i},$$

where  $\theta_{e,t}^{i}$  are inverse emission factors.

Mathematically, we solve a stochastic control problem

 $\widehat{\gamma}_{\bullet}^{i} := \arg \sup_{\gamma_{\bullet}^{i} \in \mathcal{A}^{i}} \mathcal{J}^{i} \left( \gamma_{\bullet}^{i} \right)$ 

 $\mathcal{T}^{i}\left(\gamma_{\bullet}^{i}\right) = \mathbb{E}\left[\int_{0}^{\infty} e^{-tt} \left(\operatorname{AP}^{i} \rho_{t}^{i} - \alpha_{\bullet,t}^{i,\theta} \cdot \gamma_{\bullet,t}^{i} - \beta_{\bullet,t}^{i,\theta} \cdot (\gamma^{2})_{\bullet,t}^{i} - \ell_{1}^{i} \left(1 \cdot \gamma_{\bullet,t}^{i} - \widetilde{\gamma}_{t}^{i}\right) + \ell_{2}^{i} \left(\widetilde{\gamma}_{t}^{i} - 1 \cdot \gamma_{\bullet,t}^{i}\right)\right) \mathrm{d}t$ 

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 $\begin{aligned} \widehat{\gamma}^{i}_{\bullet} &:= \arg \sup_{\gamma^{i}_{\bullet} \in \mathcal{A}^{i}} \mathcal{J}^{i}\left(\gamma^{i}_{\bullet}\right), \\ \mathcal{J}^{i}\left(\gamma^{i}_{\bullet}\right) &= \mathbb{E}\Big[\int_{0}^{\infty} e^{-rt} \left(\operatorname{AP}^{i} p^{i}_{t} - \alpha^{i,\theta}_{\bullet,t} \cdot \gamma^{i}_{\bullet,t} - \beta^{i,\theta}_{\bullet,t} \cdot (\gamma^{2})^{i}_{\bullet,t} - \ell^{i}_{1}\left(1 \cdot \gamma^{i}_{\bullet,t} - \widetilde{\gamma}^{i}_{t}\right) + \ell^{i}_{2}\left(\widetilde{\gamma}^{i}_{t} - 1 \cdot \gamma^{i}_{\bullet,t}\right)\right) \mathrm{d}t \end{aligned}$ 

# Solutions

- Under mild conditions, we have existence/uniqueness results (see the paper for details).
- Optimal emission paths may be deterministic.

#### Theorem 1

Assume 
$$\ell_1^i(x) = \omega_1^i \ x_+^2$$
 and  $\ell_2^i(x) = \omega_2^i \ x_+^2$ . For any  $t \ge 0$ , define

$$\Gamma^{i}_{t} := \frac{1}{2\beta^{i,\theta}_{\bullet,t}} \cdot \big(\frac{\operatorname{AP}^{i} c_{\bullet}^{i,\theta}}{r + b^{i}} - \alpha_{\bullet,t}^{i,\theta}\big), \quad \xi^{i}_{1,t} := \omega^{i}_{1} \left(\mathbf{1} \cdot \frac{1}{\beta^{i,\theta}_{\bullet,t}}\right), \quad \xi^{i}_{2,t} := \omega^{i}_{2} \left(\mathbf{1} \cdot \frac{1}{\beta^{i,\theta}_{\bullet,t}}\right)$$

Under a small parameter condition  $(\dots)$ , the optimal emission strategy for the energy source e has the explicit form

$$\widehat{\gamma}_{\mathbf{e},t}^{i} = \frac{1}{2\beta_{\mathbf{e},t}^{i,\theta}} \Big( \frac{\mathrm{AP}^{i} \, \boldsymbol{c}_{\mathbf{e}}^{i,\theta}}{r+b^{i}} - \alpha_{\mathbf{e},t}^{i,\theta} - \frac{2\omega_{1}^{i}}{1+\xi_{1,t}^{i}} \left(\boldsymbol{\Gamma}_{t}^{i} - \widetilde{\gamma}_{t}^{i}\right)^{+} - \frac{2\omega_{2}^{i}}{1-\xi_{2,t}^{i}} \left(\widetilde{\gamma}_{t}^{i} - \boldsymbol{\Gamma}_{t}^{i}\right)^{+} \Big).$$

Transition risks Physical risks

Optimal emissions for three types of energy (natural gas, electricity from nuclear and from coal)



# Projecting physical risks

 $\triangleright$  Types of climate extremes and weather extreme events:

$$\label{eq:cw} \begin{split} \mathcal{CW} &:= \big\{ \text{storm/typhoon/hurricane/tornado/tropical cyclone,} \\ & \text{hailstorm, flood, winter storm, level sea rise, and storm surge,} \\ & \text{heat wave, drought, wildfire, extreme cold spells, snowstorms,} ... \big\}. \end{split}$$

Occurence of climate and weather event cw at geographical zone l is modeled with Poisson process  $N^{cw,l}$ .

Cumulative loss over  $[t_0, t_1]$ :  $\int_{t_0}^{t_1} \sum_{cw,l} Z_u^{i,cw,l} dN_u^{cw,l}.$ 

▷ Expected Physical Damage (EPL) for obligor *i*:

$$\begin{split} \mathrm{EPL}^{i}(t) &:= \mathbb{E}\Big[\sum_{\mathsf{cw},l} \int_{t}^{\infty} e^{-r(u-t)} Z_{u}^{i,\mathsf{cw},l} \mathrm{d} N_{u}^{\mathsf{cw},l} \big| \mathcal{F}_{t}\Big], \\ &= \int_{t}^{\infty} e^{-r(u-t)} \Big(\sum_{\mathsf{cw},l} \mathbb{E}[Z_{u}^{i,\mathsf{cw},l}] \,\lambda_{u}^{\mathsf{cw},l} \Big) \mathrm{d} u. \end{split}$$

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Transition risks Physical risks

From the DICE model (Dynamic Integrated model of Climate and the Economy, Nordhaus 1992), the global damage increases with the atmospheric temperature  $T_{\rm ATM}$ :

 $\mathcal{D}\big(\mathcal{T}_{\mathrm{ATM}}\big) = \textit{a}_{1}\mathcal{T}_{\mathrm{ATM}} + \textit{a}_{2}\mathcal{T}_{\mathrm{ATM}}^{2}$ 

with  $a_1 = 0$ ,  $a_2 = 0.0028388$  (2008 version of DICE).



Global average temperature increase relative to the preindustrial era (year 1750) for different SSPs.

Projection in the future (using temperature SSP scenarios):

$$\operatorname{EPL}^{i}(t) := \Big(\sum_{\mathsf{cw},l} \mathbb{E}\big[Z_{t_{\operatorname{ref}}}^{i,\mathsf{cw},l}\big] \lambda_{t_{\operatorname{ref}}}^{\mathsf{cw},l} \Big) \int_{t}^{\infty} e^{-r(u-t)} \frac{\mathcal{D}(\mathcal{T}_{\operatorname{ATM}}(u))}{\mathcal{D}(\mathcal{T}_{\operatorname{ATM}}(t_{\operatorname{ref}}))} \mathrm{d}u,$$

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## Alternative to EPL

- Purpose: to better capture the full distribution of physical losses
- ${\scriptstyle \bullet}$  Using Value-at-Risk-based measure at risk level  $\alpha$
- Define PL<sup>i</sup><sub>u</sub> := ∑<sub>cw,l</sub> ∫<sup>u</sup><sub>u-1</sub> Z<sup>i,cw,l</sup><sub>s</sub> dN<sup>cw,l</sup><sub>s</sub> ds for the physical loss incurred by the *i*th obligor over a one-year period ending at time u.
- Replace  $EPL^i$  by

$$\begin{aligned} \operatorname{VaR}_{\alpha}-\operatorname{PL}^{i}(t) &= \int_{t}^{\infty} e^{-r(u-t)} \operatorname{VaR}_{\alpha} \Big[ \sum_{cw,l} \int_{u-1}^{u} Z_{s}^{i,cw,l} \, \mathrm{d}N_{s}^{cw,l} \, \mathrm{d}s \Big] \, \mathrm{d}u \\ &\approx \operatorname{VaR}_{\alpha} \big[ \operatorname{PL}_{t_{\mathrm{ref}}}^{i} \big] \int_{t}^{\infty} e^{-r(u-t)} \, \frac{\mathcal{D}(\mathcal{T}_{\mathrm{ATM}}(u))}{\mathcal{D}(\mathcal{T}_{\mathrm{ATM}}(t_{\mathrm{ref}}))} \, \mathrm{d}u. \end{aligned}$$

Portfolio loss PCA PCE Algorithms



Portfolio loss PCA PCE Algorithms

# Portfolio loss

### Recall

$$\mathcal{L}_t = \sum_{i=1}^n \Lambda^i \times \mathbf{1}_{\left\{\widehat{V}_t^i \leq L^i(t)\right\}}$$

where  $\Lambda^{i} = \text{EAD}^{i} \times \text{LGD}^{i}$  and large  $n \ (\approx 1E6)$ . Obligor firm value:

$$\begin{split} \widehat{V}_{t}^{i} &:= \mathbb{E}\Bigg[\int_{t}^{\infty} e^{-r(u-t)} \bigg( \mathrm{AP}^{i} \times \widehat{P}_{u}^{i} - \alpha_{\bullet,u}^{i,\theta} \cdot \widehat{\gamma}_{\bullet,u}^{i} - \beta_{\bullet,u}^{i,\theta} \cdot (\widehat{\gamma}^{2})_{\bullet,u}^{i} \\ &- \omega_{1}^{i} \left( \mathbf{1} \cdot \widehat{\gamma}_{\bullet,u}^{i} - \widetilde{\gamma}_{u}^{i} \right)_{+}^{2} + \omega_{2}^{i} \left( \widetilde{\gamma}_{u}^{i} - \mathbf{1} \cdot \widehat{\gamma}_{\bullet,u}^{i} \right)_{+}^{2} \bigg) \mathrm{d}u \bigg| \mathcal{F}_{t} \Bigg] - \mathrm{EPL}^{i}(t), \end{split}$$

After some computations:  $\mathcal{L}_t = \sum_{i=1}^n \Lambda^i \mathbf{1}_{\left\{A_t^i \leq X_t^i\right\}}$  with

 $\begin{aligned} A_t^i &:= \sqrt{1 - (\rho^i)^2} \int_0^t e^{-b^i(t-s)} dB_s^i + \text{ deterministic function of time } t, \\ X_t^i &:= -\rho^i \int_0^t e^{-b^i(t-s)} dB_s. \end{aligned}$ 

 $\underline{\wedge}$  Time consuming to sample.

Portfolio loss PCA PCE Algorithms

# PCA approximation

Consider  $X_t := (X_t^i)_{1 \le i \le n}$  with covariance matrix

$$(K_{X_t})^{i,j} := \operatorname{Cov}(X_t^i, X_t^j) = \rho^i \rho^j \int_0^t e^{-b^i(t-s)} e^{-b^j(t-s)} \mathrm{d}s = \rho^i \rho^j \frac{1 - e^{-(b'+b')t}}{b^i + b^j}.$$



Figure: Ratio  $\frac{\nu^k}{\nu^1}$  for k from 1 to 10 with n = 1000,  $\rho \sim \mathcal{U}[-1,1]$  and  $b \sim \mathcal{U}[0,1]$ ,  $\mathcal{U}[1,4]$ , and  $\mathcal{U}[0,10]$ .



Mostly, only two eigenvalues matter !! So far, lack of quantitative estimates.

Portfolio loss PCA PCE Algorithms

## PCA error bound

Approximate PCA model:

$$\mathcal{L}_t \approx \mathcal{L}_t^{\text{PCA}} := \sum_{i=1}^n \Lambda^i \, \mathbf{1}_{\left\{A_t^i \leq \sqrt{\nu^1} G^1 u^{\mathbf{1},i} + \sqrt{\nu^2} G^2 u^{\mathbf{2},i}\right\}}$$

#### Theorem 2

The  $L_1$  error between the original and approximated loss is bounded as follows:

$$\mathbb{E}\left[\left|\mathcal{L}_t - \mathcal{L}_t^{\text{PCA}}\right|\right] \leq \sum_{i=1}^n \frac{\Lambda^i}{\pi} \frac{|\rho^i|}{\sqrt{1 - (\rho^i)^2}} \sqrt{\frac{\sum_{k=3}^n \nu^k (u^{k,i})^2}{\sum_{k=1}^n \nu^k (u^{k,i})^2}}.$$

Portfolio loss PCA **PCE** Algorithms

## Polynomial chaos expansion

$$\mathcal{L}_{t}^{\text{PCA}} = \sum_{i=1}^{n} \Lambda^{i} \mathbf{1}_{\left\{\frac{A_{t}^{i}}{\sqrt{\nu^{1}(u^{1,i})^{2} + \nu^{2}(u^{2,i})^{2}} \le \frac{\sqrt{\nu^{1}u^{1,i}G^{1} + \sqrt{\nu^{2}}u^{2,i}G^{2}}}{\sqrt{\nu^{1}(u^{1,i})^{2} + \nu^{2}(u^{2,i})^{2}}}\right\} \text{ with } (\mathcal{L}^{1,i})^{2} + (\mathcal{L}^{2,i})^{2} = 1$$

$$=: \sum_{i=1}^{n} \Lambda^{i} \mathbf{1}_{\left\{\tilde{A}_{t}^{i} \le \mathcal{L}^{1,i}G^{1} + \mathcal{L}^{2,i}G^{2}\right\}}$$

$$\approx \sum_{i=1}^{n} \Lambda^{i} \sum_{m=0}^{M} \tau_{m}(\tilde{A}_{t}^{i}) \operatorname{He}_{m}(\mathcal{L}^{1,i}G^{1} + \mathcal{L}^{2,i}G^{2}) \quad (\text{Hermite polynomial chaos expansion})$$

$$= \sum_{i=1}^{n} \Lambda^{i} \sum_{m=0}^{M} \tau_{m}(\tilde{A}_{t}^{i}) \sum_{\substack{m_{1},m_{2} \ge 0 \\ m_{1}+m_{2}=m}}} \frac{m!}{m_{1}!m_{2}!} (\mathcal{L}^{1,i})^{m_{1}} (\mathcal{L}^{2,i})^{m_{2}} \operatorname{He}_{m_{1}}(G^{1}) \operatorname{He}_{m_{2}}(G^{2})$$

$$= \sum_{m=0}^{M} \sum_{\substack{m_{1},m_{2} \ge 0 \\ m_{1}+m_{2}=m}} \frac{m!}{m_{1}!m_{2}!} \operatorname{He}_{m_{1}}(G^{1}) \operatorname{He}_{m_{2}}(G^{2}) \underbrace{\sum_{i=1}^{n} \Lambda^{i} \tau_{m}(\tilde{A}_{t}^{i})(\mathcal{L}^{1,i})^{m_{1}} (\mathcal{L}^{2,i})^{m_{2}}}_{\sim \text{Gaussian (CLT, } n \to +\infty)}$$

 $L_2$  Error control of the PCE:  $(\sum_{i=1}^{n} \Lambda^i) M^{-\frac{1}{4}}$ , see [BGR20] and [BGR22, Theorem 2.7] In practice, taking M small is enough.

Portfolio loss PCA PCE Algorithms

## Polynomial chaos expansion

$$\begin{split} \mathcal{L}_{t}^{\text{PCA}} &= \sum_{i=1}^{n} \Lambda^{i} \, \mathbf{1}_{\left\{\frac{\Lambda_{t}^{i}}{\sqrt{\nu^{1}(u^{1,i})^{2} + \nu^{2}(u^{2,i})^{2}}} \leq \frac{\sqrt{\nu^{1}u^{1,i}G^{1} + \sqrt{\nu^{2}}u^{2,i}G^{2}}}{\sqrt{\nu^{1}(u^{1,i})^{2} + \nu^{2}(u^{2,i})^{2}}}\right\} \text{ with } (\mathcal{L}^{1,i})^{2} + (\mathcal{L}^{2,i})^{2} = 1 \\ &=: \sum_{i=1}^{n} \Lambda^{i} \, \mathbf{1}_{\left\{\tilde{A}_{t}^{i} \leq \mathcal{L}^{1,i}G^{1} + \mathcal{L}^{2,i}G^{2}\right\}} \\ &\approx \sum_{i=1}^{n} \Lambda^{i} \, \sum_{m=0}^{M} \tau_{m}(\tilde{A}_{t}^{i}) \operatorname{He}_{m}(\mathcal{L}^{1,i}G^{1} + \mathcal{L}^{2,i}G^{2}) \quad (\text{Hermite polynomial chaos expansion}) \\ &= \sum_{i=1}^{n} \Lambda^{i} \, \sum_{m=0}^{M} \tau_{m}(\tilde{A}_{t}^{i}) \sum_{\substack{m_{1},m_{2} \geq 0 \\ m_{1}+m_{2}=m}} \frac{m!}{m_{1}!m_{2}!} (\mathcal{L}^{1,i})^{m_{1}}(\mathcal{L}^{2,i})^{m_{2}} \operatorname{He}_{m_{1}}(G^{1}) \operatorname{He}_{m_{2}}(G^{2}) \\ &= \sum_{m=0}^{M} \sum_{\substack{m_{1},m_{2} \geq 0 \\ m_{1}+m_{2}=m}} \frac{m!}{m_{1}!m_{2}!} \operatorname{He}_{m_{1}}(G^{1}) \operatorname{He}_{m_{2}}(G^{2}) \underbrace{\sum_{i=1}^{n} \Lambda^{i} \tau_{m}(\tilde{A}_{t}^{i})(\mathcal{L}^{1,i})^{m_{1}}(\mathcal{L}^{2,i})^{m_{2}}}_{\sim \text{Gaussian (CLT, } n \to +\infty)} \end{split}$$

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Portfolio loss PCA **PCE** Algorithms

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$$\begin{split} \mathcal{L}_{t}^{\text{PCA}} &= \sum_{i=1}^{n} \Lambda^{i} \mathbf{1}_{\left\{\frac{A_{t}^{i}}{\sqrt{\nu^{1}(u^{1,i})^{2} + \nu^{2}(u^{2,i})^{2}}} \leq \frac{\sqrt{\nu^{1}u^{1,i}G^{1} + \sqrt{\nu^{2}u^{2,i}G^{2}}}{\sqrt{\nu^{1}(u^{1,i})^{2} + \nu^{2}(u^{2,i})^{2}}}\right\} \text{ with } (\mathcal{L}^{1,i})^{2} + (\mathcal{L}^{2,i})^{2} = 1 \\ &=: \sum_{i=1}^{n} \Lambda^{i} \mathbf{1}_{\left\{\tilde{A}_{t}^{i} \leq \mathcal{L}^{1,i}G^{1} + \mathcal{L}^{2,i}G^{2}\right\}} \\ &\approx \sum_{i=1}^{n} \Lambda^{i} \sum_{m=0}^{M} \tau_{m}(\tilde{A}_{t}^{i}) \operatorname{He}_{m}(\mathcal{L}^{1,i}G^{1} + \mathcal{L}^{2,i}G^{2}) \quad (\text{Hermite polynomial chaos expansion}) \\ &= \sum_{i=1}^{n} \Lambda^{i} \sum_{m=0}^{M} \tau_{m}(\tilde{A}_{t}^{i}) \sum_{\substack{m_{1},m_{2} \geq 0 \\ m_{1}+m_{2}=m}} \frac{m!}{m_{1}!m_{2}!} (\mathcal{L}^{1,i})^{m_{1}}(\mathcal{L}^{2,i})^{m_{2}} \operatorname{He}_{m_{1}}(G^{1}) \operatorname{He}_{m_{2}}(G^{2}) \\ &= \sum_{m=0}^{M} \sum_{\substack{m_{1},m_{2} \geq 0 \\ m_{1}+m_{2}=m}} \frac{m!}{m_{1}!m_{2}!} \operatorname{He}_{m_{1}}(G^{1}) \operatorname{He}_{m_{2}}(G^{2}) \underbrace{\sum_{i=1}^{n} \Lambda^{i} \tau_{m}(\tilde{A}_{t}^{i})(\mathcal{L}^{1,i})^{m_{1}}(\mathcal{L}^{2,i})^{m_{2}}}_{\sim \text{Gaussian (CLT, } n \to +\infty)} =: \mathcal{L}_{t}^{\text{PCA,PCE}}. \end{split}$$

 $L_2$  Error control of the PCE:  $(\sum_{i=1}^{n} \Lambda^i) M^{-\frac{1}{4}}$ , see [BGR20] and [BGR22, Theorem 2.7] In practice, taking M small is enough.

Portfolio loss PCA PCE Algorithms

# Computational gain

 $\mathit{n}=10,000$  obligors,  $\mathit{n}_{\mathrm{mc}}=10^5$  Monte Carlo samples

Algorithm 1: Crude Monte Carlo:	Algorithm 2: Monte Carlo: Sampling of the
Sampling of the portfolio loss $\mathcal{L}_t$	PCA-PCE portfolio loss with Gaussian approximation
$\label{eq:constraint} \begin{array}{ c c c } \hline \textbf{Output:} & n_{\mathrm{mc}} \text{ i.i.d. samples of } \mathcal{L}_t; \\ \hline \textbf{for } j \leftarrow 1 \text{ to } n_{\mathrm{mc}} \text{ do} \\ \hline \textbf{Compute vector of optimal} \\ & \text{emissions } (\widehat{\gamma}_t^1, \dots, \widehat{\gamma}_t^n); \\ \textbf{Sample Gaussian vector} \\ & (\widehat{\rho}_t^1, \dots, \widehat{\rho}_t^n); \\ \textbf{Compute vector of optimal} \\ & \text{values } (\widehat{V}_t^1, \dots, \widehat{V}_t^n); \\ \textbf{Compute the portfolio loss} \\ & \mathcal{L}_t = \sum_{i=1}^n \Lambda^i \times 1_{\left\{ \widehat{V}_t^i \leq L^i(t) \right\}}. \end{array}$	Output: $n_{mc}$ i.i.d. samples of $\mathcal{L}_{t}^{PCA,PCE,G}$ ; Offline computation: Find PCA decomposition of $K_{X_{t}}$ ; Compute parameters for the PCE; for $j \leftarrow 1$ to $n_{mc}$ do Sample $\left(\varepsilon_{n,m_{1},m_{2}}^{G}\right)_{m_{1}+m_{2}=m,0\leq m\leq M} \sim \mathcal{N}(\mathcal{M},\mathcal{K})$ ; Sample two independent $G^{1}, G^{2} \sim \mathcal{N}(0,1)$ ; Compute PCA-PCE portfolio loss $\mathcal{L}_{t}^{PCA,PCE,G} =$ $\sum_{m=0}^{M} \sum_{m_{1},m_{2}>0} \varepsilon_{n,m_{1},m_{2}}^{G} \operatorname{Hem}_{1}(G^{1})\operatorname{Hem}_{2}(G^{2})$
Algorithm 1 or 75 seconds	$m_1 + m_2 = m$

- Algorithm 1  $\approx$  75 seconds - Algorithm 2  $\approx$  2 seconds.

Impact of physical risks PCA approximation PCE approximation

### Numerical experiments

We focus on three distinct SSP scenarios: SSP1-26, SSP3-70 (Baseline), and SSP5-85 (Baseline) for the transportation sector.

The portfolio loss maturity is set at t = 5 years, where t = 0 corresponds to 2015. We take  $n_{\rm mc} = 10^5$  Monte Carlo samples for our analysis.

We study the fictitious portfolio with parameters:

• 
$$t = 5$$
 years,  $n = 1,000$ ,  $r = 2\%$ ,

• 3 different energy sources for e,  $c_{e}^{i} = (0.01, 0.01, 0.01)$ ,  $\alpha_{\bullet,t}^{i} = (0,0,0)$ ,  $\beta_{\bullet,t}^{i} = (0.1, 0.5, 0.8)$ ,  $\theta_{\bullet,t}^{i} = (1,1,1)$ ,

• 
$$\omega_1 = 0.05$$
,  $\omega_2 = 0.02$ ,

• 
$$P_0 = 1$$
,  $\sigma^i \stackrel{\text{i.i.d.}}{\sim} \mathcal{U}[0, \frac{1}{2}]$ ,  $a^i \stackrel{\text{i.i.d.}}{\sim} \mathcal{U}[0, \frac{1}{2}]$ ,  $b^i \stackrel{\text{i.i.d.}}{\sim} \mathcal{U}[1, 4]$ ,  
 $\rho^i \stackrel{\text{i.i.d.}}{\sim} \mathcal{U}[-1, 1]$ ,  $\Lambda^i = \frac{1}{\sqrt{i}}$ ,  $AP^i = 1$ ,  $\lambda_{ref} = 3\%$ .

• Initial physical damage:  $0.001\% \times \hat{V}_0^i$ .

Impact of physical risks PCA approximation PCE approximation

## Impact of physical risks



Figure: Portfolio losses with and without physical risk for the scenarios SSP1-26, SSP3-70, and SSP5-85.

 $\triangle$  As expected, incorporating a physical risk term significantly shifts the portfolio loss distribution upward.

Impact of physical risks **PCA approximation** PCE approximation

# Impact of Principal Component Analysis



Figure: Portfolio loss  $\mathcal{L}$  and two-factor-PCA-approximated loss  $\mathcal{L}^{PCA}$  for the scenarios SSP1-26, SSP3-70, and SSP5-85 (top figures) and associated Q-Q plots (bottom figures).

Impact of physical risks PCA approximation **PCE approximation** 

# Impact of Polynomial Chaos Expansion



Figure: Comparison of  $\mathcal{L}$  and  $\mathcal{L}^{PCA,PCE,G}$  (left figures) and associated Q-Q plots (right figures) with M = 1, 3, 5, 10 for the scenarios SSP1-26, SSP3-70, and SSP5-85.

# Conclusion

- End-to-end methodology to assess the credit risk of a large portfolio of obligors
- Impact of transition and physical climate risks, given a SSP scenario
- Efficient computations using two steps-reduction techniques (Principal Component Analysis and Polynomial Chaos Expansion)
- Work-in-progress: dealing with real data

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